







Model Curriculum

QP Name: Automotive Robotics and Automation Simulation Engineer

QP Code: ASC/Q8305

QP Version: 1.0

NSQF Level: 6

Model Curriculum Version: 1.0

Automotive Skills Development Council | 153, Gr Floor, Okhla Industrial Area, Phase – III, Leela Building, New Delhi – 110020







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Training Parameters

Sector	Automotive
Sub-Sector	Manufacturing
Occupation	Automotive Product Development
Country	India
NSQF Level	6
Aligned to NCO/ISCO/ISIC Code	NCO-2015/1223.0101ÿ
Minimum Educational Qualification and Experience	M.E./M.Tech in the relevant field OR B.E./B.Tech in the relevant field with 1 Year of relevant experience, OR 3 years Diploma (Mechanical/Automobile/Electrical / Electronics) after class 12th from recognized regulatory body with 3 years of relevant experience OR Certificate-NSQF (Automotive Prototype Manufacturing Lead Technician Level 5) with 3 Years of relevant experience
Pre-Requisite License or Training	NA
Minimum Job Entry Age	22 years
Last Reviewed On	28 th July, 2022
Next Review Date	28 th July, 2025
NSQC Approval Date	28 th July, 2022
QP Version	1.0
Model Curriculum Creation Date	28 th July, 2022
Model Curriculum Valid Up to Date	28 th July, 2025
Model Curriculum Version	1.0
Minimum Duration of the Course	570 Hours
Maximum Duration of the Course	570 Hours







Program Overview

This section summarizes the end objectives of the program along with its duration.

Training Outcomes

At the end of the program, the learner should have acquired the listed knowledge and skills.

- Prepare for simulation and testing of automation systems.
- Perform selection, designing and layouting of industrial robot.
- Perform integration of robots and automation system.
- Perform simulation and testing of robots and automation system.
- Work effectively and efficiently as per schedules and timelines.
- Implement safety practices.
- Use resources optimally to ensure less wastage and maximum conservation.
- Communicate effectively and develop interpersonal skills.

Compulsory Modules

The table lists the modules and their duration corresponding to the Compulsory NOS of the QP.

NOS and Module Details	Theory Duration	Practical Duration	On-the-Job Training Duration (Mandatory)	On-the-Job Training Duration (Recommended)	Total Duration
Bridge Module					
Module 1: Introduction to the role of an Automotive Robotics and Automation Simulation Engineer	5:00	0:00			5:00
ASC/N9810: Manage work and resources					
(Manufacturing) NOS Version No. – 1.0 NSQF Level – 5	20:00	40:00			60:00
Module 2: Manage work and resources according to safety and conservation standards	20:00	40:00			60:00
ASC/N9812 – Interact effectively with team, customers and others NOS Version No. 1.0 NSQF Level 5	20:00	35:00			55:00
Module 3: Communicate effectively and efficiently	20:00	35:00			55:00
ASC/N8313 – Prepare for simulation and integration of robot and automation system NOS Version No. –1.0 NSQF Level - 6	15:00	55:00	80:00		150:00
Module 4: Prepare for simulation and integration of	15:00	55:00	80:00		150:00







robot and automation system				
ASC/N8314- Selection, designing and layouting of robot and automation system NOS Version No1.0 NSQF Level - 6	15:00	55:00	80:00	150:00
Module 5: Selection, designing and layouting of robot and automation system	15:00	55:00	80:00	150:00
ASC/N8315 – Simulation and integration of robot and automation system NOS Version No. –1.0 NSQF Level - 6	15:00	55:00	80:00	150:00
Module 6: Simulation and integration of robot and automation system	15:00	55:00	80:00	150:00
Total Duration	90:00	240:00	240:00	570:00







Module Details

Module 1: Introduction to the role of an Automotive Robotics and Automation Simulation Engineer

Bridge module

Terminal Outcomes:

• Discuss the role and responsibilities of an Automotive Robotics and Automation Simulation Engineer.

Duration : <05:00>	Duration : <00:00>
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 List the role and responsibilities of an Automotive Robotics and Automation Simulation Engineer. Discuss the job opportunities for an Automotive Robotics and Automation Simulation Engineer in the automobile industry. Explain about Indian automobile manufacturing market. List various automobile Original Equipment Manufacturers (OEMs) and different products/ models manufactured by them. Discuss automation and manufacturing standards and procedures followed in the company. 	
Classroom Aids:	
Whiteboard, marker pen, projector	
Tools, Equipment and Other Requirements	





disposal mechanism depending upon

types of waste.



Module 2: Manage work and resources according to safety and conservation standards

Mapped to ASC/N9810, v1.0

Terminal Outcomes:

- Employ appropriate ways to maintain safe and secure working environment

Key Learning Outcomes
y appropriate ways to implement ty practices to ensure safety of people e workplace. lay the correct way of wearing and osing PPE. onstrate the use of fire extinguisher. onstrate how to provide first aid edure in case of emergencies. onstrate how to evacuate the typlace in case of an emergency. loy various techniques for checking unctions in the machines with the ort of maintenance team and as per dard Operating Procedures (SOP). onstrate to arrange tools/ pment/ fasteners/ spare parts into eer trays, cabinets, lockers as tioned in the 5S guidelines/work uctions. y appropriate ways to organise safety sor training sessions for others on the tified risks and safety practices. are a report about the health, safety security breaches. y appropriate ways to check that typlace, equipment, restrooms etc. are ned and sanitised. play a situation to brief the team the hygiene and sanitation lations developed by organisation. onstrate the correct way of washing is using soap and water and alcohol- d hand rubs. y appropriate methods to support the loyees to cope with stress, anxiety
n c e

availability of running water, hand wash

and alcohol-based sanitizers at the







workplace.

- Discuss the significance of conforming to basic hygiene practices such as washing hands, using alcohol based hand sanitizers or soap.
- Recall ways of reporting advanced hygiene and sanitation issues to the concerned authorities.
- Elucidate various stress and anxiety management techniques.
- Discuss the significance of greening.
- Classify different categories of waste for the purpose of segregation.
- Differentiate between recyclable and nonrecyclable waste.
- Discuss various methods of waste collection and disposal.
- List the various materials used at the workplace.
- Explain organisational recommended norms for storage of tools, equipment and material.
- Discuss the importance of efficient utilisation of material and water.
- Explain basics of electricity and prevalent energy efficient devices.
- Explain the processes to optimize usage of material and energy/electricity.
- Enlist common practices for conserving electricity at workplace.

- Perform the steps involved in storage of tools, equipment and material after completion of work.
- Employ appropriate ways to resolve malfunctioning (fumes/ sparks/ emission/ vibration/ noise) and lapse in maintenance of equipment as per requirements.
- Perform the steps to prepare a sample material and energy audit reports.
- Employ practices for efficient utilization of material and energy/electricity.

Classroom Aids:

Whiteboard, marker pen, projector

Tools, Equipment and Other Requirements

- Housekeeping material: Cleaning agents, cleaning cloth, waste container, dust pan and brush set, liquid soap, hand towel, fire extinguisher
- Safety gears: Safety shoes, ear plug, goggles, gloves, helmet, first-aid kit







Module 3: Communicate Effectively and Efficiently

Mapped to ASC/N9812, v1.0

Terminal Outcomes:

- Use effective communication and interpersonal skills.
- Apply sensitivity while interacting with different genders and people with disabilities.

Ouration: <20:00>	Duration: <35:00>
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
Explain the importance of complying with organizational requirements to share information with team members. Discuss the ways to adjust the communication styles to reflect sensitivity towards gender and persons with disability (PwD). Explain the importance of respecting personal space of colleagues and customers. Describe the ways to manage and coordinate with team members for work integration. State the importance of team goals over individual goals, keeping commitment made to team members, and informing them in case of delays. Discuss the importance of following the organisation's policies and procedures Discuss the importance of rectifying errors as per feedback and minimizing mistakes. Discuss gender-based concepts, issues and legislation as well organization standards, guidelines, rights and duties of PwD. Discuss the importance of PwD and gender sensitization to ensure that team shows sensitivity towards them. State the importance of following organizational standards and guidelines related to PwD. Recall the rights and duties at workplace with respect to PwD. Outline organisation policies and procedures pertaining to written and	 Employ different means and methods of communication depending upon the requirement to interact with the team members. Employ appropriate ways to maintain good relationships with team members and superiors. Apply appropriate techniques to resolve conflicts and manage team members for smooth workflow. Conduct training sessions to train the team members on proper reporting of completed work and receiving feedback. Employ suitable ways to escalate problems to superiors as and when required. Prepare a sample report on the progress and team performance. Role play a situation on how to offer help to people with disability (PwD) if required at work.

Whiteboard/blackboard, marker/chalk, duster, computer or Laptop attached to LCD projector

Tools, Equipment and Other Requirements







Module 4: Prepare for simulation and integration of robot and automation system Mapped to ASC/N8313, v1.0

Terminal Outcomes:

Duration: <15:00>

- Perform the steps of preparing for simulation and integration of robot and automation system.
- Demonstrate organisational procedure of planning for the simulation and integration of robot and automation system.

Duration: <55:00>

Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Discuss the information obtained from the product documents like stitch sheet or joining sheets, product drawings and other engineering documents. Discuss the selection criteria of automation elements in align with electrical, mechanical and environmental parameters. List all the components to be joined in a particular production cell. Discuss core and auxiliary support process required during automation process. Discuss the information obtained from assembly plan, weld line process plan, Production BOM and Production/Assembly documents. Describe sequence of operations for the integration activities. Describe Standard work cycle. List sequence of joining/production activities. Discuss potential failures in process. Describe FMEA and CAPA. Discuss the records and documents needed to be prepared as a reference for future development. 	 Employ appropriate ways to design / interpret the project design from the product drawings and other engineering documents. Demonstrate Standard operation procedures recommended by manufacturer for using equipment / machinery. Show how to identify inputs and outputs in a robotic cell. Prepare sample assembly plan and sequence of operations for the integration activities. Plan material loading and unloading sequence in the robotic cell. Prepare sample weld line process plan based on Engineering and Production BOM. Apply appropriate ways to collect production volume and data of available time for the production. Apply appropriate ways to calculate total work to be done to size the production line. Show how to read Production/Assembly documents to find out material handling points and other jigs/fixture and equipment required for integration. Plan sequence of joining/production activities. Prepare sample weld line specification and Process Flow Diagram for new model. Apply appropriate ways to identify potential failures in process. Perform steps to conduct FMEA of the process. Prepare CAPA and execution targets of the process.







Classroom Aids:

Whiteboard, marker pen, projector

Tools, Equipment and Other Requirements

PCs/Laptops, Internet with Wi-Fi (Min2 Mbps Dedicated)

18 documents of PPAP, Design records, Design Records, Authorized Engineering Change Documents, Customer Engineering Approval, Design Failure Modes and Effects Analysis (DFMEA), applied in special situations, Process Flow Diagram, Process Failure Modes and Effects Analysis (PFMEA) Control Plan, Part Submission Warrant (PSW), Engineering Change Documents

Dimensional Results, PLC Simulator, Hydraulic, Pneumatic, Electronic Control Systems Simulator, Internet of Things study material and IOT communication devices, Manufacturing Execution system, manufacturing operation management system.

Hydraulics and pneumatics systems simulator, PLC Simulator with required software, Air Cylinders, valves, connector/tubing simulators, Pick and place robots assembly

Electronics sensor like proximity, optical, magnetic sensors.







Module 5: Selection, designing and layouting of robot and automation system Mapped to ASC/N8314, v1.0

Terminal Outcomes:

- Perform preparatory activities like robot selection, preparation of mounting design, etc.
- Demonstrate organisational procedure of selection, designing and layouting of robot and automation system.

Duration: <15:00>	Duration: <55:00>		
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes		
 Discuss the information obtained from the project document related to the robots and automation system requirements. Discuss the information obtained from manual and technical specification of robots. Describe the selection criteria of industrial robot based on applications, robot types and technical parameters. Describe pay load, reachability and accuracy requirements of the robot in application. Describe types of end effector and their selection criteria. Describe the selection criteria of type of gun (X-Type or C-Type) in case of spot welding and welding torch in case of arc welding. Describe the functioning of ATC and its need in robotic system. Describe the functioning and use of components of robotic cell like robot, tip dressers, jigs/fixture/grippers, Docking units, sensor and cable trays etc. Describe tolerance & matching quality fit and finish. List the steps to be performed for robot integration with automation elements. 	 Employ appropriate ways to design / interpret the project document from the information related to robots and automation system requirements. Apply appropriate ways to determine pay load, reachability and accuracy requirements of the robot in application. Show how to determine maximum load of the EOAT. Show how to select gun (X-Type or C-Type) in case of spot welding and welding torch in case of arc welding. Show how to determine Gun Depth and gap between arm, force and power exerted by the gun in case of spot welding. Apply appropriate ways to plan material space, trolleys, supply of material to line side & material handling equipment. Show how to find the position of equipment and finalize robot positions. Prepare a sample 2D drawing of equipment position. Show how to generate the foot prints of plant. Read the project document to identify the application of the new equipment. Apply appropriate ways to finalize the PLPs, clamp plan and clamp opening angles and orientation of loading and unloading at stations. Show how to determine the mounting, TCP of equipment and pneumatic circuit of clamps. 		

Whiteboard, marker pen, projector

Tools, Equipment and Other Requirements

PCs/Laptops, Internet with Wi-Fi (Min2 Mbps Dedicated)

18 documents of PPAP, Design records, Design Records, Authorized Engineering Change







Documents, Customer Engineering Approval, Design Failure Modes and Effects Analysis (DFMEA), applied in special situations, Process Flow Diagram, Process Failure Modes and Effects Analysis (PFMEA) Control Plan, Part Submission Warrant (PSW), Engineering Change Documents

Dimensional Results, PLC Simulator, Hydraulic, Pneumatic, Electronic Control Systems Simulator, Internet of Things study material and IOT communication devices, Manufacturing Execution system, manufacturing operation management system.

Hydraulics and pneumatics systems simulator, PLC Simulator with required software, Air Cylinders, valves, connector/tubing simulators, Pick and place robots assembly Electronics sensor like proximity, optical, magnetic sensors.







Module 6: Simulation and integration of robot and automation system Mapped to ASC/N8315, v1.0

Terminal Outcomes:

- Perform steps for simulation of robot and automation system.
- Demonstrate organisational procedure of integrating robots and automation

Duration : <15:00>	Duration : <55:00>
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Describe simulation techniques for checking the reachability and feasibility of the robot. Discuss the selection criteria of automation elements in align with electrical, mechanical and environmental parameters. Elaborate accuracy, speed and motion of robot. Describe various kinematics properties of the robotic system. Describe various weld quality parameters and their impact on the system. List the steps to be performed for integration of the robot controller in simulation software. List the steps to be performed for creating OLP. 	 Perform steps to create robotic operations like spot weld, arc welding, handling and sealing & gluing. Show how to create and project MFGs and welds on product. Show how to create welding seams on product. Apply appropriate ways to check the weld reachability by the assigned robot and feasibility of gun/torch with car product. Apply appropriate ways to check and report collisions of EOATs with other equipment and products. Prepare the simulation results in required formats. Perform steps to define the kinematics i.e. links and mechanism in equipment, joints in links, device operation program, poses at diff. opening and closing points etc. of the equipment. Apply appropriate ways to calculate no. of link for angular openings. Perform steps to install robot controller licenses into the system and integrate robot controller and robot. Show how to feed machine data file to the controller and define sequence of multiple paths/Operation. Show how to assign weld parameters in the weld path. Apply appropriate ways to create collision free path of the robot. Show how to modify path to achieve cycle time.

Classroom Aids:

Whiteboard, marker pen, projector

Tools, Equipment and Other Requirements

PCs/Laptops, Internet with Wi-Fi (Min2 Mbps Dedicated)

18 documents of PPAP, Design records, Design Records, Authorized Engineering Change







Documents, Customer Engineering Approval, Design Failure Modes and Effects Analysis (DFMEA), applied in special situations, Process Flow Diagram, Process Failure Modes and Effects Analysis (PFMEA) Control Plan, Part Submission Warrant (PSW), Engineering Change Documents

Dimensional Results, PLC Simulator, Hydraulic, Pneumatic, Electronic Control Systems Simulator, Internet of Things study material and IOT communication devices, Manufacturing Execution system, manufacturing operation management system.

Hydraulics and pneumatics systems simulator, PLC Simulator with required software, Air Cylinders, valves, connector/tubing simulators, Pick and place robots assembly Electronics sensor like proximity, optical, magnetic sensors.







Annexure

Trainer Requirements

Trainer Prerequisites						
Minimum Educational	Specialization	Relevant Industry Experience		Training Experience		Remar ks
Qualification		Years	Specialization	Yea rs	Specialization	
B.E/B.Tech	Mechanical/Autom obile/ Electrical/ Electronics	4	Mechanical/ Automobile/ Electronics/ Instrumentation	1	Mechanical/ Automobile/ Electronics/ Instrumentation	NA
B.E/B.Tech	Mechanical/Autom obile/ Electrical/ Electronics	5	Mechanical/ Automobile/ Electronics/ Instrumentation	0	Mechanical/ Automobile/ Electronics/ Instrumentation	NA
Diploma	Mechanical/Autom obile/ Electrical/ Electronics	3	Mechanical/ Automobile/ Electronics	1	Mechanical/ Automobile/ Electronics	NA
Diploma	Mechanical/Autom obile/ Electrical/ Electronics	4	Mechanical/ Automobile/ Electronics	0	Mechanical/ Automobile/ Electronics	NA
M.E/M.Tech	Mechanical/Autom obile/ Electrical/ Electronics	2	Mechanical/Aut omobile/ Electrical/ Electronics	1	Mechanical/Automo bile/ Electrical/ Electronics	NA
M.E/M.Tech	Mechanical/Autom obile/ Electrical/ Electronics	3	Mechanical/Aut omobile/ Electrical/ Electronics	0	Mechanical/Automo bile/ Electrical/ Electronics	NA

Trainer Certification				
Domain Certification	Platform Certification			
"Automotive Robotics and Automation Simulation	"Trainer, MEP/Q2601 v1.0" Minimum accepted score is			
Engineer, ASC/Q8305, version 1.0". Minimum accepted score is 80%.	80%.			







Assessor Requirements

Assessor Prerequisites							
Minimum Educational Qualification	Specialization	Relevant Industry Experience		Training Experience		Remar ks	
		Year s	Specialization	Yea rs	Specialization		
B.E/B.Tech	Mechanical/Autom obile/ Electrical/ Electronics	5	Mechanical/ Automobile/ Electronics/ Instrumentation	1	Mechanical/ Automobile/ Electronics/ Instrumentation	NA	
B.E/B.Tech	Mechanical/Autom obile/ Electrical/ Electronics	6	Mechanical/ Automobile/ Electronics/ Instrumentation	0	Mechanical/ Automobile/ Electronics/ Instrumentation	NA	
Diploma	Mechanical/Autom obile/ Electrical/ Electronics	4	Mechanical/ Automobile/ Electronics	1	Mechanical/ Automobile/ Electronics	NA	
Diploma	Mechanical/Autom obile/ Electrical/ Electronics	5	Mechanical/ Automobile/ Electronics	0	Mechanical/ Automobile/ Electronics	NA	
M.E/M.Tech	Mechanical/Autom obile/ Electrical/ Electronics	3	Mechanical/Auto mobile/ Electrical/ Electronics	1	Mechanical/Automo bile/ Electrical/ Electronics	NA	
M.E/M.Tech	Mechanical/Autom obile/ Electrical/ Electronics	4	Mechanical/Auto mobile/ Electrical/ Electronics	0	Mechanical/Automo bile/ Electrical/ Electronics	NA	

Assessor Certification					
Domain Certification	Platform Certification				
"Automotive Robotics and Automation Simulation	"Assessor; MEP/Q2701 v1.0"				
Engineer, ASC/Q8305, version 1.0". Minimum accepted score is 80%.	Minimum accepted score is 80%.				







Assessment Strategy

1. Assessment System Overview:

- Batches assigned to the assessment agencies for conducting the assessment on SDMS/SIP or email
- Assessment agencies send the assessment confirmation to VTP/TC looping SSC
- Assessment agency deploys the ToA certified Assessor for executing the assessment
- SSC monitors the assessment process & records

2. Testing Environment:

- Confirm that the centre is available at the same address as mentioned on SDMS or SIP
- Check the duration of the training.
- Check the Assessment Start and End time to be as 10 a.m. and 5 p.m.
- If the batch size is more than 30, then there should be 2 Assessors.
- Check that the allotted time to the candidates to complete Theory & Practical Assessment is correct.
- Check the mode of assessment—Online (TAB/Computer) or Offline (OMR/PP).
- Confirm the number of TABs on the ground are correct to execute the Assessment smoothly.
- Check the availability of the Lab Equipment for the particular Job Role.

3. Assessment Quality Assurance levels / Framework:

- Question papers created by the Subject Matter Experts (SME)
- Question papers created by the SME verified by the other subject Matter Experts
- Questions are mapped with NOS and PC
- Question papers are prepared considering that level 1 to 3 are for the unskilled & semi-skilled individuals, and level 4 and above are for the skilled, supervisor & higher management
- Assessor must be ToA certified & trainer must be ToT Certified
- Assessment agency must follow the assessment guidelines to conduct the assessment

4. Types of evidence or evidence-gathering protocol:

- Time-stamped & geotagged reporting of the assessor from assessment location
- Centre photographs with signboards and scheme specific branding
- Biometric or manual attendance sheet (stamped by TP) of the trainees during the training period
- Time-stamped & geotagged assessment (Theory + Viva + Practical) photographs & videos

5. Method of verification or validation:

- Surprise visit to the assessment location
- Random audit of the batch
- Random audit of any candidate

6. Method for assessment documentation, archiving, and access

- Hard copies of the documents are stored
- Soft copies of the documents & photographs of the assessment are uploaded / accessed from Cloud Storage
- Soft copies of the documents & photographs of the assessment are stored in the Hard Drives







References

Glossary

Term	Description
Declarative Knowledge	Declarative knowledge refers to facts, concepts and principles that need to be known and/or understood in order to accomplish a task or to solve a problem.
Key Learning Outcome	Key learning outcome is the statement of what a learner needs to know, understand and be able to do in order to achieve the terminal outcomes. A set of key learning outcomes will make up the training outcomes. Training outcome is specified in terms of knowledge, understanding (theory) and skills (practical application).
OJT (M)	On-the-job training (Mandatory); trainees are mandated to complete specified hours of training on site
OJT (R)	On-the-job training (Recommended); trainees are recommended the specified hours of training on site
Procedural Knowledge	Procedural knowledge addresses how to do something, or how to perform a task. It is the ability to work, or produce a tangible work output by applying cognitive, affective or psychomotor skills.
Training Outcome	Training outcome is a statement of what a learner will know, understand and be able to do upon the completion of the training.
Terminal Outcome	Terminal outcome is a statement of what a learner will know, understand and be able to do upon the completion of a module. A set of terminal outcomes help to achieve the training outcome.







Acronyms and Abbreviations

NOS	National Occupational Standard(s)	
NSQF	National Skills Qualifications Framework	
QP	Qualifications Pack	
TVET	Technical and Vocational Education and Training	
SOP	Standard Operating Procedure	
WI	Work Instructions	
PPE	Personal Protective equipment	